

# ATV212HU22N4

variable speed drive ATV212 - 2.2kW - 3hp -  
480V - 3ph - EMC - IP21



## Main

|                              |                                    |
|------------------------------|------------------------------------|
| Range of product             | Altivar 212                        |
| Product or component type    | Variable speed drive               |
| Device short name            | ATV212                             |
| Product destination          | Asynchronous motors                |
| Product specific application | Pumps and fans in HVAC             |
| Assembly style               | With heat sink                     |
| Network number of phases     | 3 phases                           |
| Motor power kW               | 2.2 kW                             |
| Motor power hp               | 3 hp                               |
| Power supply voltage         | 380...480 V (- 15...10 %)          |
| Power supply voltage limits  | 323...528 V                        |
| Supply frequency             | 50...60 Hz (- 5...5 %)             |
| Network frequency            | 47.5...63 Hz                       |
| EMC filter                   | Class C2 EMC filter integrated     |
| Line current                 | 3.6 A for 480 V<br>4.6 A for 380 V |

## Complementary

|                                       |  |
|---------------------------------------|--|
| Apparent power                        | 3.9 kVA for 380 V  |
| Prospective line I <sub>sc</sub>      | 5 kA   |
| Continuous output current             | 5.1 A at 380/460 V   |
| Maximum transient current             | 5.6 A for 60 s   |
| Speed drive output frequency          | 0.5...200 Hz   |
| Nominal switching frequency           | 12 kHz   |
| Switching frequency                   | 6...16 kHz adjustable<br>12...16 kHz with derating factor  |
| Speed range                           | 1...10   |
| Speed accuracy                        | +/- 10 % of nominal slip for 0.2 T <sub>n</sub> to T <sub>n</sub> torque variation   |
| Torque accuracy                       | +/- 15 %   |
| Transient overtorque                  | 120 % of nominal motor torque for 60 s   |
| Asynchronous motor control profile    | Voltage/Frequency ratio, 2 points<br>Voltage/Frequency ratio, 5 points<br>Flux vector control without sensor, standard<br>Voltage/Frequency ratio - Energy Saving, quadratic U/f<br>Voltage/Frequency ratio, automatic IR compensation (U/f + automatic U <sub>0</sub> ) |
| Regulation loop                       | Adjustable PI regulator  |
| Motor slip compensation               | Adjustable<br>Automatic whatever the load<br>Not available in voltage/frequency ratio motor control  |
| Local signalling                      | 1 LED - red - DC bus energized   |
| Output voltage                        | <= power supply voltage  |
| Isolation                             | Electrical between power and control   |
| Type of cable for external connection | IEC cable without mounting kit: 1 wire(s) - 45 °C, copper 90 °C / XLPE/EPR<br>IEC cable without mounting kit: 1 wire(s) - 45 °C, copper 70 °C / PVC<br>UL 508 cable with UL Type 1 kit: 3 wire(s) - 40 °C, copper 75 °C / PVC  |
| Electrical connection                 | Terminal 2.5 mm <sup>2</sup> / AWG 14 (VIA, VIB, FM, FLA, FLB, FLC, RY, RC, F, R, RES)<br>Terminal 6 mm <sup>2</sup> / AWG 10 (L1/R, L2/S, L3/T)   |

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

|                                     |   |
|-------------------------------------|---|
| Tightening torque                   | 0.6 N.m (VIA, VIB, FM, FLA, FLB, FLC, RY, RC, F, R, RES)<br>1.3 N.m - 11.5 lb.in (L1/R, L2/S, L3/T)   |
| Supply                              | Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC, +/- 5 % -<br><= 10 A with overload and short-circuit protection<br>Internal supply: 24 V (21...27 V) DC - <= 200 A with overload and short-circuit<br>protection   |
| Analogue input number               | 2   |
| Analogue input type                 | Configurable PTC probe: (VIB) 0...6 probes - 1500 Ohm<br>Switch-configurable voltage: (VIA) 0...10 V DC - 24 V max - 30000 Ohm -<br>resolution: 10 bits<br>Switch-configurable current: (VIA) 0...20 mA - 250 Ohm - resolution: 10 bits<br>Configurable voltage: (VIB) 0...10 V DC - 24 V max - 30000 Ohm - resolution: 10<br>bits  |
| Sampling duration                   | 2 ms +/- 0.5 ms (F) - discrete input(s)<br>2 ms +/- 0.5 ms (R) - discrete input(s)<br>2 ms +/- 0.5 ms (RES) - discrete input(s)<br>3.5 ms +/- 0.5 ms (VIA) - analog input(s)<br>22 ms +/- 0.5 ms (VIB) - analog input(s)  |
| Response time                       | 2 ms +/- 0.5 ms (FM) - analog output(s)<br>7 ms +/- 0.5 ms (FLA, FLC) - discrete output(s)<br>7 ms +/- 0.5 ms (FLB, FLC) - discrete output(s)<br>7 ms +/- 0.5 ms (RY, RC) - discrete output(s)  |
| Accuracy                            | +/- 0.6 % (VIA) for a temperature variation 60 °C<br>+/- 0.6 % (VIB) for a temperature variation 60 °C<br>+/- 1 % (FM) for a temperature variation 60 °C  |
| Linearity error                     | +/- 0.15 % of maximum value for input (VIA)<br>+/- 0.15 % of maximum value for input (VIB)<br>+/- 0.2 % for output (FM)   |
| Analogue output number              | 1   |
| Analogue output type                | Switch-configurable voltage: (FM) 0...10 V DC - 7620 Ohm - resolution: 10 bits<br>Switch-configurable current: (FM) 0...20 mA - 970 Ohm - resolution: 10 bits   |
| Discrete output number              | 2   |
| Discrete output type                | Configurable relay logic: (FLA, FLC) NO - 100000 cycles<br>Configurable relay logic: (FLB, FLC) NC - 100000 cycles<br>Configurable relay logic: (RY, RC) NO - 100000 cycles   |
| Minimum switching current           | 3 mA at 24 V DC (configurable relay logic)  |
| Maximum switching current           | 5 A at 250 V AC on resistive load - cos phi = 1 - L/R = 0 ms (FL, R)<br>5 A at 30 V DC on resistive load - cos phi = 1 - L/R = 0 ms (FL, R)<br>2 A at 250 V AC on inductive load - cos phi = 0.4 - L/R = 7 ms (FL, R)<br>2 A at 30 V DC on inductive load - cos phi = 0.4 - L/R = 7 ms (FL, R)  |
| Discrete input type                 | Programmable (F) 24 V DC, with level 1 PLC - 4700 Ohm<br>Programmable (R) 24 V DC, with level 1 PLC - 4700 Ohm<br>Programmable (RES) 24 V DC, with level 1 PLC - 4700 Ohm   |
| Discrete input logic                | Positive logic (source) (F, R, RES), <= 5 V (state 0), >= 11 V (state 1)<br>Negative logic (sink) (F, R, RES), >= 16 V (state 0), <= 10 V (state 1)   |
| Acceleration and deceleration ramps | Automatic based on the load<br>Linear adjustable separately from 0.01 to 3200 s   |
| Braking to standstill               | By DC injection   |
| Protection type                     | Overheating protection for drive<br>Thermal power stage for drive<br>Short-circuit between motor phases for drive<br>Input phase breaks for drive<br>Overcurrent between output phases and earth for drive<br>Overvoltages on the DC bus for drive<br>Break on the control circuit for drive<br>Against exceeding limit speed for drive<br>Line supply overvoltage and undervoltage for drive<br>Line supply undervoltage for drive<br>Against input phase loss for drive<br>Thermal protection for motor<br>Motor phase break for motor<br>With PTC probes for motor |
| Dielectric strength                 | 3535 V DC between earth and power terminals<br>5092 V DC between control and power terminals  |
| Insulation resistance               | >= 1 MOhm at 500 V DC for 1 minute  |
| Frequency resolution                | 0.1 Hz for display unit<br>0.024/50 Hz for analog input   |

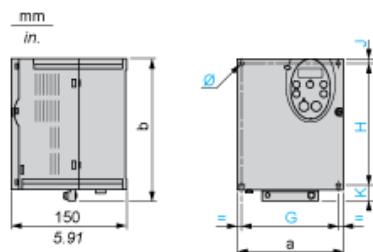
|                             |   |
|-----------------------------|---|
| Communication port protocol | APOGEE FLN<br>BACnet<br>LonWorks<br>METASYS N2<br>Modbus  |
| Connector type              | 1 RJ45<br>1 open style  |
| Physical interface          | 2-wire RS 485   |
| Transmission frame          | RTU   |
| Transmission rate           | 9600 bps or 19200 bps   |
| Data format                 | 8 bits, 1 stop, odd even or no configurable parity  |
| Type of polarization        | No impedance  |
| Number of addresses         | 1...247   |
| Communication service       | Monitoring inhibitable<br>Read device identification (43)<br>Read holding registers (03) 2 words maximum<br>Time out setting from 0.1 to 100 s<br>Write multiple registers (16) 2 words maximum<br>Write single register (06) |
| Option card                 | Communication card for LonWorks   |
| Operating position          | Vertical +/- 10 degree  |
| Width                       | 107 mm  |
| Height                      | 143 mm  |
| Depth                       | 150 mm  |
| Product weight              | 2 kg  |
| Power dissipation in W      | 103 W   |
| Fan flow rate               | 35 m3/h   |

## Environment

|                                       |   |
|---------------------------------------|---|
| Electromagnetic compatibility         | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2<br>Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3<br>Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4<br>1.2/50 $\mu$ s - 8/20 $\mu$ s surge immunity test level 3 conforming to IEC 61000-4-5<br>Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6<br>Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
| Pollution degree                      | 3 IEC 61800-5-1   |
| IP degree of protection               | IP21 conforming to EN/IEC 61800-5-1<br>IP21 conforming to EN/IEC 60529<br>IP41 on upper part conforming to EN/IEC 61800-5-1<br>IP41 on upper part conforming to EN/IEC 60529<br>IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5-1<br>IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529  |
| Vibration resistance                  | 1.5 mm (f = 3...13 Hz) conforming to EN/IEC 60068-2-6<br>1 gn (f = 13...200 Hz) conforming to EN/IEC 60068-2-8  |
| Shock resistance                      | 15 gn for 11 ms conforming to IEC 60068-2-27  |
| Environmental characteristic          | Classes 3C1 conforming to IEC 60721-3-3<br>Classes 3S2 conforming to IEC 60721-3-3  |
| Noise level                           | 51 dB conforming to 86/188/EEC  |
| Relative humidity                     | 5...95 % without condensation conforming to IEC 60068-2-3<br>5...95 % without dripping water conforming to IEC 60068-2-3  |
| Operating altitude                    | <= 1000 m without derating<br>1000...3000 m (limited to 2000 m for the Corner Grounded distribution network)<br>with current derating 1 % per 100 m   |
| Ambient air temperature for operation | -10...40 °C without derating<br>> 40...50 °C with derating factor   |
| Ambient air temperature for storage   | -25...70 °C   |

|                        |   |
|------------------------|---|
| Standards              | EN 55011 class A group 1<br>EN 61800-3<br>EN 61800-3 category C2<br>EN 61800-3 category C3<br>EN 61800-3 environments 1 category C1<br>EN 61800-3 environments 1 category C2<br>EN 61800-3 environments 1 category C3<br>EN 61800-3 environments 2 category C1<br>EN 61800-3 environments 2 category C2<br>EN 61800-3 environments 2 category C3<br>EN 61800-5-1<br>IEC 61800-3<br>IEC 61800-3 category C2<br>IEC 61800-3 category C3<br>IEC 61800-3 environments 1 category C1<br>IEC 61800-3 environments 1 category C2<br>IEC 61800-3 environments 1 category C3<br>IEC 61800-3 environments 2 category C1<br>IEC 61800-3 environments 2 category C2<br>IEC 61800-3 environments 2 category C3<br>IEC 61800-5-1<br>UL Type 1 |
| Product certifications | CSA<br>C-Tick<br>NOM 117<br>UL  |
| Marking                | CE  |

Dimensions



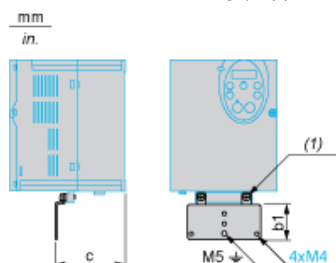
Dimensions in mm

| ATV212H                          | a   | b   | G   | H     | J   | K    | Ø      |
|----------------------------------|-----|-----|-----|-------|-----|------|--------|
| 075M3X...U22M3X<br>075N4...U22N4 | 107 | 143 | 93  | 121.5 | 5   | 16.5 | 2 x Ø5 |
| U30M3X, U40M3X<br>U30N4...U55N4  | 142 | 184 | 126 | 157   | 6.5 | 20.5 | 4 x Ø5 |

Dimensions in in.

| ATV212H                          | a    | b    | G    | H    | J    | K    | Ø         |
|----------------------------------|------|------|------|------|------|------|-----------|
| 075M3X...U22M3X<br>075N4...U22N4 | 4.21 | 5.63 | 3.66 | 4.78 | 0.20 | 0.65 | 2 x Ø0.20 |
| U30M3X, U40M3X<br>U30N4...U55N4  | 5.59 | 7.24 | 4.96 | 6.18 | 0.26 | 0.81 | 4 x Ø0.20 |

Plate for EMC mounting (supplied with the drive)



(1) 2 x M5 screws

Dimensions in mm

| ATV212H                          | b1 | c    |
|----------------------------------|----|------|
| 075M3X...U22M3X<br>075N4...U22N4 | 49 | 67.3 |
| U30M3X, U40M3X<br>U30N4...U55N4  | 48 | 88.8 |

Dimensions in in.

| ATV212H                          | b1   | c    |
|----------------------------------|------|------|
| 075M3X...U22M3X<br>075N4...U22N4 | 1.93 | 2.65 |
| U30M3X, U40M3X<br>U30N4...U55N4  | 1.89 | 3.50 |

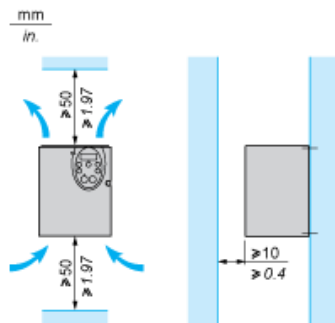
## Mounting Recommendations

### Clearance

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

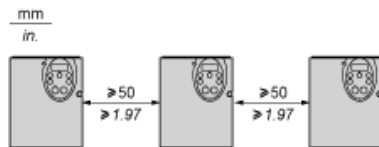
Install the unit vertically:

- Do not place it close to heating elements.
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from bottom to the top of the unit.

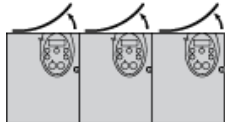


### Mounting Types

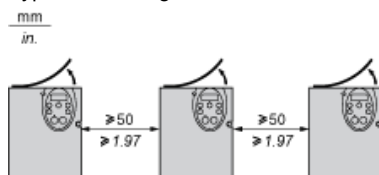
#### Type A mounting



#### Type B mounting



#### Type C mounting



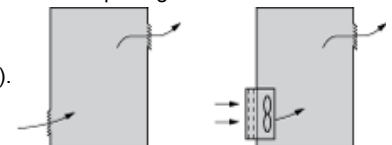
By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP21. The protective blanking cover may vary according to the drive model, see opposite.

## Specific Recommendations for Mounting in an Enclosure

To help ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Check that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must

provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



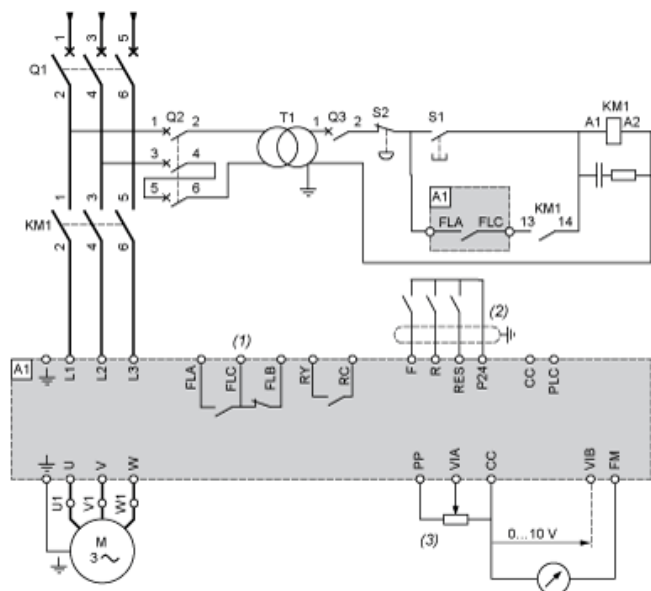
- Use special filters with UL Type 12/IP54 protection.
- Remove the blanking cover from the top of the drive.

## Sealed Metal Enclosure (IP54 Degree of Protection)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions, such as dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

Recommended Wiring Diagram

3-Phase Power Supply



- A1: ATV 212 drive
- KM1: Contactor
- Q1: Circuit breaker
- Q2: GV2 L rated at twice the nominal primary current of T1
- Q3: GB2CB05
- S1, XB4 B or XB5 A pushbuttons
- S2:
- T1: 100 VA transformer 220 V secondary
- (1) Fault relay contacts for remote signalling of the drive status
- (2) Connection of the common for the logic inputs depends on the positioning of the switch (Source, PLC, Sink)
- (3) Reference potentiometer SZ1RV1202

All terminals are located at the bottom of the drive. Install interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Switches (Factory Settings)

Voltage/current selection for analog I/O (VIA and VIB)



Voltage/current selection for analog I/O (FM)



Selection of logic type



- (1) negative logic
- (2) positive logic

Other Possible Wiring Diagrams

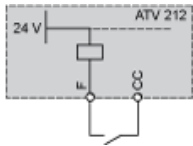


## Logic Inputs According to the Position of the Logic Type Switch

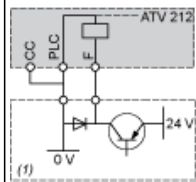
"Source" position



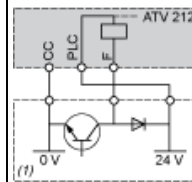
"Sink" position



"PLC" position with PLC transistor outputs

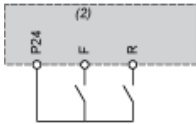


(1) PLC



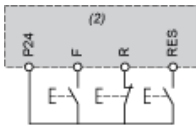
(1) PLC

2-wire control



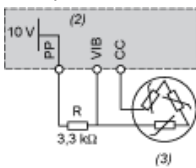
F: Forward  
R: Preset speed  
(2) ATV 212 control terminals

3-wire control



F: Forward  
R: Stop  
RES: Reverse  
(2) ATV 212 control terminals

PTC probe

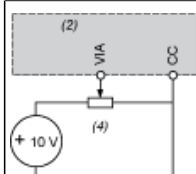


(2) ATV 212 control terminals  
(3) Motor

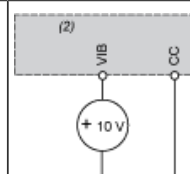
## Analogue Inputs

Voltage analogue inputs

External +10 V



(2) ATV 212 control terminals  
(4) Speed reference potentiometer 2.2 to 10 kΩ



(2) ATV 212 control terminals

Analog input configured for current: 0-20 mA, 4-20 mA, X-Y mA



(2) ATV 212 control terminals

(5) Source 0-20 mA, 4-20 mA, X-Y mA

Analog input VIA configured as positive logic input ("Source" position)



(2) ATV 212 control terminals

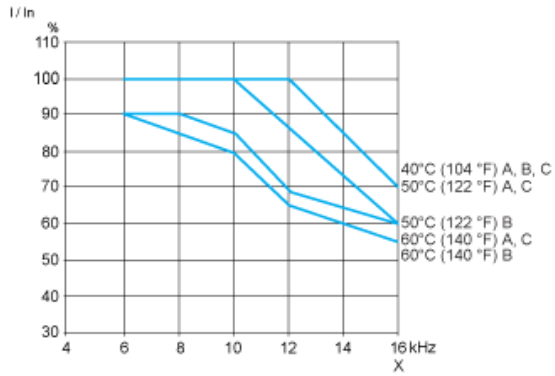
Analog input VIA configured as negative logic input ("Sink" position)



(2) ATV 212 control terminals

Derating Curves

The derating curves for the drive nominal current ( $I_n$ ) depend on the temperature, the switching frequency and the mounting type (A, B or C). For intermediate temperatures (45°C for example), interpolate between 2 curves.



X Switching frequency