

# 4G bits GDDR5 SGRAM

## EDW4032BABG (128M words x 32 bits)

### Specifications

- Density: 4G bits
- Organization
  - 8Mbit x 32 I/O x 16 banks
  - 16Mbit x 16 I/O x 16 banks
- Package
  - 170-ball FBGA
  - Lead-free (RoHS compliant) and Halogen-free
- Power supply:
  - VDD: 1.6V/1.5V ± 3% and 1.35V ± 3%
  - VDDQ: 1.6V/1.5V ± 3% and 1.35V ± 3%
- Data rate: 7.0Gbps/6.0Gbps (max.)
- 16 internal banks
- Four bank groups for tCCDL = 3tCK
- 8n prefetch architecture: 256 bit per array Read or Write access for x32; 128 bit for x16
- Burst length (BL): 8 only
- Programmable CAS latency: 6 to 22
- Programmable Write latency: 3 to 7
- Programmable CRC READ latency: 1 to 3
- Programmable CRC WRITE latency: 8 to 14
- Programmable EDC hold pattern for CDR
- Precharge: auto precharge option for each burst access
- Refresh: auto-refresh, self-refresh
- Refresh cycles: 16384 cycles/32ms
- Interface: Pseudo open drain (POD-15)
- On-die termination (ODT): nom. values of 60Ω or 120Ω
- Pseudo open drain (POD-15) compatible outputs
  - 40Ω pulldown
  - 60Ω pullup
- ODT and output driver strength auto-calibration with external resistor ZQ pin (120Ω)
- Programmable termination and driver strength offsets
- Selectable external or internal VREF for data inputs; programmable offsets for internal VREF
- Separate external VREF for address / command inputs
- Operating case temperature range
  - TC = 0°C to +95°C

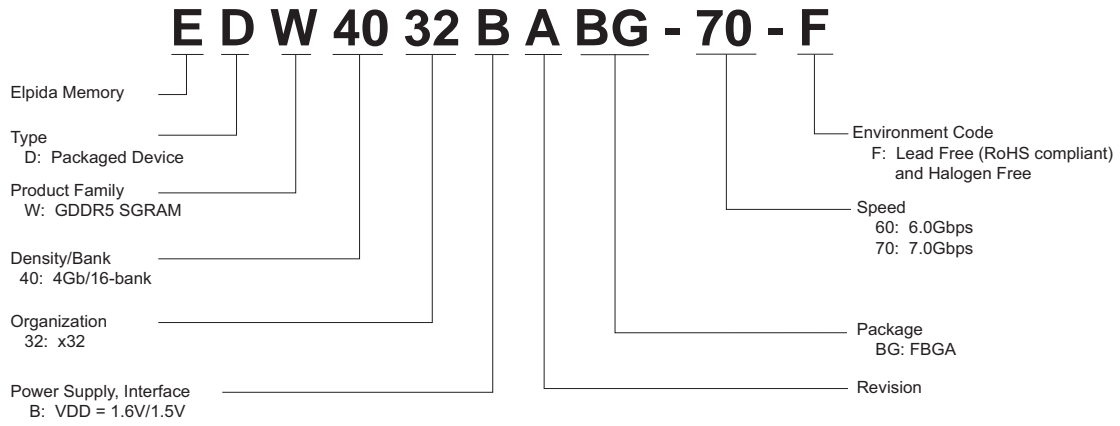
### Features

- x32/x16 mode configuration set at power-up with EDC pin
- Single ended interface for data, address and command
- Quarter data-rate differential clock inputs CK\_t, CK\_c for address and commands
- Two half data-rate differential clock inputs WCK\_t, WCK\_c, each associated with two data bytes (DQ, DBI\_n, EDC)
- Double Data Rate (DDR) data (WCK)
- Single Data Rate (SDR) command (CK)
- Double Data Rate (DDR) addressing (CK)
- Write data mask function via address bus (single/double byte mask)
- Data Bus Inversion (DBI) and Address Bus Inversion (ABI)
- Input/output PLL on/off mode
- Duty cycle corrector (DCC) for data clock (WCK)
- Address training: address input monitoring via DQ pins
- WCK2CK clock training: phase information via EDC pins
- Data read and write training via Read FIFO (FIFO depth = 6)
- Read FIFO pattern preload by LDFF command
- Direct write data load to Read FIFO by WRTR command
- Consecutive read of Read FIFO by RDTR command
- Read/Write data transmission integrity secured by cyclic redundancy check (CRC-8)
- Read/Write EDC on/off mode
- DQ Preamble for Read on/off mode
- Low Power modes
- RDQS mode on EDC pin
- On-chip temperature sensor with read-out
- Automatic temperature sensor controlled self-refresh rate
- Digital RAS lockout
- Vendor ID, FIFO depth and Density info fields for identification
- Mirror function with MF pin
- Boundary Scan function with SEN pin

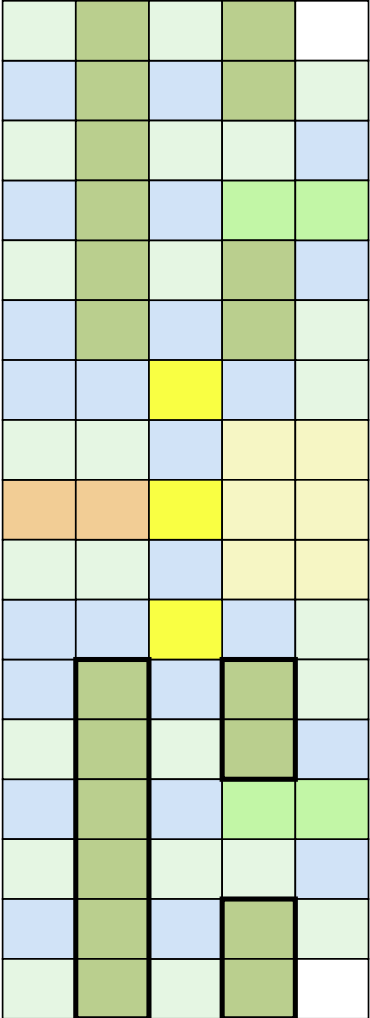
Ordering Information

Part number	Organization (words x bits)	VDD, VDDQ	Max. Data Rate	Package
EDW4032BABG-60-F	128M x 32	1.5V / 1.35V	6.0Gbps / 5.0Gbps	170-ball FBGA
EDW4032BABG-70-F		1.6V / 1.35V	7.0Gbps / 5.0Gbps	

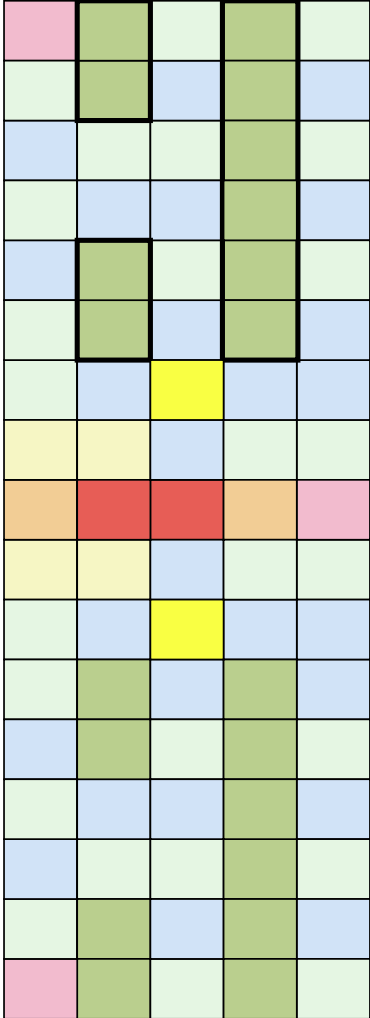
Part Number



Pin Configuration



□



170-ball FBGA (MF=1 Configuration)

1	2	3	4	5	6	7	8	9	10	11	12	13	14
VSSQ	DQ25	VSSQ	DQ24	NC					VREFD	DQ16	VSSQ	DQ17	VSSQ
VDDQ	DQ27	VDDQ	DQ26	VSS					VSS	DQ18	VDDQ	DQ19	VDDQ
VSSQ	EDC3	VSSQ	VSSQ	VDD					VDD	VSSQ	VSSQ	EDC2	VSSQ
VDDQ	DBI3_n	VDDQ	WCK23_t	WCK23_c					VSS	VDD	VDDQ	DBI2_n	VDDQ
VSSQ	DQ29	VSSQ	DQ28	VDDQ					VDDQ	DQ20	VSSQ	DQ21	VSSQ
VDDQ	DQ31	VDDQ	DQ30	VSSQ					VSSQ	DQ22	VDDQ	DQ23	VDDQ
VDD	VDDQ	CAS_n	VDD	VSS					VSS	VDD	WE_n	VDDQ	VDD
VSS	VSSQ	VDDQ	A8 A7	A11 A6					BA1 A5	BA2 A4	VDDQ	VSSQ	VSS
MF	RESET_n	CKE_n	ABI_n	A12 A13					SEN	CK_c	CK_t	ZQ	VREFC
VSS	VSSQ	VDDQ	A10 A0	A9 A1					BA3 A3	BA0 A2	VDDQ	VSSQ	VSS
VDD	VDDQ	RAS_n	VDD	VSS					VSS	VDD	CS_n	VDDQ	VDD
VDDQ	DQ7	VDDQ	DQ6	VSSQ					VSSQ	DQ14	VDDQ	DQ15	VDDQ
VSSQ	DQ5	VSSQ	DQ4	VDDQ					VDDQ	DQ12	VSSQ	DQ13	VSSQ
VDDQ	DBI0_n	VDDQ	WCK01_t	WCK01_c					VSS	VDD	VDDQ	DBI1_n	VDDQ
VSSQ	EDC0	VSSQ	VSSQ	VDD					VDD	VSSQ	VSSQ	EDC1	VSSQ
VDDQ	DQ3	VDDQ	DQ2	VSS					VSS	DQ10	VDDQ	DQ11	VDDQ
VSSQ	DQ1	VSSQ	DQ0	NC					VREFD	DQ8	VSSQ	DQ9	VSSQ

□ = pin is OFF in x16 mode

(Top View)

Signal	Function	Signal	Function
CK_t, CK_c	Clock	ZQ	Impedance Reference
WCK01_t, WCK01_c, WCK23_t, WCK23_c	Data Clocks	RESET_n	Reset
CKE_n	Clock Enable	MF	Mirror Function
CS_n	Chip Select	SEN	Scan Enable
RAS_n, CAS_n, WE_n	Command inputs	VREFC	Reference voltage for command and address
BA0 - BA3	Bank Address inputs	VREFD	Reference voltage for DQ and DBI_n
A0 - A13	Address inputs	VDDQ	I/O power
DQ0 - DQ31	Data Input/Output	VSSQ	I/O ground
DBI0_n - DBI3_n	Data bus inversion	VDD	Power supply
EDC0 - EDC3	Error Detection Code	VSS	Ground
ABI_n	Address bus inversion	NC	Not connected

## 1. Configuration

The Elpida GDDR5 SGRAM is a high speed dynamic random-access memory designed for applications requiring high bandwidth. It contains 4,294,967,296 bits and is internally configured as a 16-bank DRAM.

The GDDR5 SGRAM uses a 8n prefetch architecture and DDR interface to achieve high-speed operation. The device can be configured to operate in x32 mode or x16 (clamshell) mode. The mode is detected during device initialization. The GDDR5 interface transfers two 32 bit wide data words per WCK clock cycle to/from the I/O pins. Corresponding to the 8n prefetch a single write or read access consists of a 256 bit wide, two CK clock cycle data transfer at the internal memory core and eight corresponding 32 bit wide one-half WCK clock cycle data transfers at the I/O pins.

The GDDR5 SGRAM operates from a differential clock CK<sub>t</sub> and CK<sub>c</sub>. Commands are registered at every rising edge of CK<sub>t</sub>. Addresses are registered at every rising edge of CK<sub>t</sub> and every rising edge of CK<sub>c</sub>.

GDDR5 replaces the pulsed strobes (WDQS & RDQS) used in previous DRAMs such as GDDR4 with a free running differential forwarded clock (WCK<sub>t</sub>, WCK<sub>c</sub>) with both input and output data registered and driven respectively at both edges of the forwarded WCK.

Read and write accesses to the GDDR5 SGRAM are burst oriented; an access starts at a selected location and continues for a total of eight data words. Accesses begin with the registration of an ACTIVE command, which is then followed by a READ or WRITE command. The address bits registered coincident with the ACTIVE command and the next rising CK<sub>c</sub> edge are used to select the bank and the row to be accessed. The address bits registered coincident with the READ or WRITE command and the next rising CK<sub>c</sub> edge are used to select the bank and the column location for the burst access.

## 1.1 Signal Description

**Table 1: Signal Description**

Signal	Type	Detailed Function
CK_t, CK_c	Input	Clock: CK_t and CK_c are differential clock inputs. Command inputs are latched on the rising edge of CK_t. Address inputs are latched on the rising edge of CK_t and the rising edge of CK_c. All latencies are referenced to CK_t. CK_t and CK_c are externally terminated.
WCK01_t, WCK01_c, WCK23_t, WCK23_c	Input	Data Clocks: WCK_t and WCK_c are differential clocks used for WRITE data capture and READ data output. WCK01_t, WCK01_c is associated with DQ0-DQ15, DBI0_n, DBI1_n, EDC0 and EDC1. WCK23_t, WCK23_c is associated with DQ16-DQ31, DBI2_n, DBI3_n, EDC2 and EDC3. WCK clocks operate at nominally twice the CK clock frequency.
CKE_n	Input	Clock Enable: CKE_n low activates and CKE_n high deactivates internal clock, device input buffers and output drivers. Taking CKE_n high provides Precharge Power-Down and Self-Refresh operations (all banks idle), or Active Power-Down (row active in any bank). CKE_n is synchronous for Power-Down entry and exit and for Self-Refresh entry. CKE_n must be maintained low throughout READ and WRITE accesses. Input buffers excluding CK_t, CK_c, CKE_n, WCK01_t, WCK01_c, WCK23_t, WCK23_c are disabled during Power-Down. Input buffers excluding CKE_n are disabled during Self-Refresh. The value of CKE_n latched at power-up with RESET_n going high determines the termination value of the address and command inputs.
CS_n	Input	Chip Select: CS_n low enables, and CS_n high disables the command decoder. All commands are masked when CS_n is registered high, but internal command execution continues. CS_n provides for individual device selection on memory channels with multiple memory devices. CS_n is considered part of the command code.
RAS_n, CAS_n, WE_n	Input	Command inputs: RAS_n, CAS_n and WE_n (along with CS_n) define the command to be entered.
BA0 - BA3	Input	Bank Address inputs: BA0-BA3 define to which bank an ACTIVE, READ, WRITE or PRECHARGE command is being applied. BA0-BA3 also determine which Mode Register is accessed with a MODE REGISTER SET command. BA0-BA3 are sampled with the rising edge of CK_t.
A0 - A13	Input	Address inputs: A0-A13 provide the row address for ACTIVE commands. A0-A5(A6) provide the column address and A8 defines the auto precharge function for READ and WRITE commands, to select one location out of the memory array in the respective bank. A8 sampled during a PRECHARGE command determines whether the PRECHARGE applies to one bank (A8 low, bank selected by BA0-BA3) or all banks (A8 high). The address inputs also provide the op-code during an MODE REGISTER SET command, and the data bits during LDFF commands. A8-A12 are sampled with the rising edge of CK_t and A0-A7, A13 are sampled with the rising edge of CK_c.
DQ0 - DQ31	I/O	Data Input/Output: 32 bit data bus
DBI0_n - DBI3_n	I/O	Data bus inversion: DBI0_n is associated with DQ0-DQ7, DBI1_n with DQ8-DQ15, DBI2_n with DQ16-DQ23, and DBI3_n with DQ24-DQ31.
EDC0 - EDC3	Output	Error Detection Code: The calculated CRC data is transmitted on these pins. In addition these pins drive a hold pattern when idle and can be used as an RDQS function. EDC0 is associated with DQ0-DQ7, EDC1 with DQ8-DQ15, EDC2 with DQ16-DQ23, and EDC3 with DQ24-DQ31.
ABI_n	Input	Address bus inversion
ZQ	-	Impedance Reference: external reference pin for auto-calibration
RESET_n	Input	Reset: VDDQ CMOS input. A full chip reset may be performed at any time by pulling RESET_n low. With RESET_n low all ODTs are disabled.
MF	Input	Mirror Function: VDDQ CMOS input. Must be tied to Power or Ground.
SEN	Input	Scan Enable: VDDQ CMOS input. Must be tied to Ground when not in use.
VREFC	Supply	Reference voltage for command and address inputs.
VREFD	Supply	Reference voltage for DQ and DBI_n inputs.
VDDQ	Supply	Isolated power for the input and output buffers.
VSSQ	Supply	Isolated ground for the input and output buffers.
VDD	Supply	Power supply
VSS	Supply	Ground
NC	-	Not connected

## 1.2 Mirror Function Mode

The GDDR5 SGRAM provides a mirror function (MF) pin to change the physical location of the command, address, data and WCK pins assisting in routing devices back to back. The MF ball should be tied directly to VSSQ or VDDQ depending on the control line orientation desired.

The pins affected by this Mirror Function mode are listed in [Table 2](#).

**Table 2: Ball Assignment with Mirror Function**

Ball	Signal		Ball	Signal		Ball	Signal		Ball	Signal	
	MF=0	MF=1		MF=0	MF=1		MF=0	MF=1		MF=0	MF=1
A2	DQ1	DQ25	A4	DQ0	DQ24	K5	A11 A6	A9 A1	G12	CS_n	WE_n
B2	DQ3	DQ27	B4	DQ2	DQ26	P5	WCK23_c	WCK01_c	L12	WE_n	CS_n
C2	EDC0	EDC3	D4	WCK01_t	WCK23_t	H10	BA3 A3	BA1 A5	A13	DQ9	DQ17
D2	DBI0_n	DBI3_n	E4	DQ4	DQ28	K10	BA1 A5	BA3 A3	B13	DQ11	DQ19
E2	DQ5	DQ29	F4	DQ6	DQ30	A11	DQ8	DQ16	C13	EDC1	EDC2
F2	DQ7	DQ31	H4	A10 A0	A8 A7	B11	DQ10	DQ18	D13	DBI1_n	DBI2_n
M2	DQ31	DQ7	K4	A8 A7	A10 A0	E11	DQ12	DQ20	E13	DQ13	DQ21
N2	DQ29	DQ5	M4	DQ30	DQ6	F11	DQ14	DQ22	F13	DQ15	DQ23
P2	DBI3_n	DBI0_n	N4	DQ28	DQ4	H11	BA0 A2	BA2 A4	M13	DQ23	DQ15
R2	EDC3	EDC0	P4	WCK23_t	WCK01_t	K11	BA2 A4	BA0 A2	N13	DQ21	DQ13
T2	DQ27	DQ3	T4	DQ26	DQ2	M11	DQ22	DQ14	P13	DBI2_n	DBI1_n
U2	DQ25	DQ1	U4	DQ24	DQ0	N11	DQ20	DQ12	R13	EDC2	EDC1
G3	RAS_n	CAS_n	D5	WCK01_c	WCK23_c	T11	DQ18	DQ10	T13	DQ19	DQ11
L3	CAS_n	RAS_n	H5	A9 A1	A11 A6	U11	DQ16	DQ8	U13	DQ17	DQ9

Functions within the GDDR5 SGRAM that refer to external signals are transparent with respect to Mirror Function mode, meaning that the signal names shown in the respective functional description apply both to mirrored (MF=1) and non-mirrored (MF=0) modes. The referenced package pin is determined by the Mirror Function mode the devices is configured to.

## 1.3 Clamshell Mode Detection

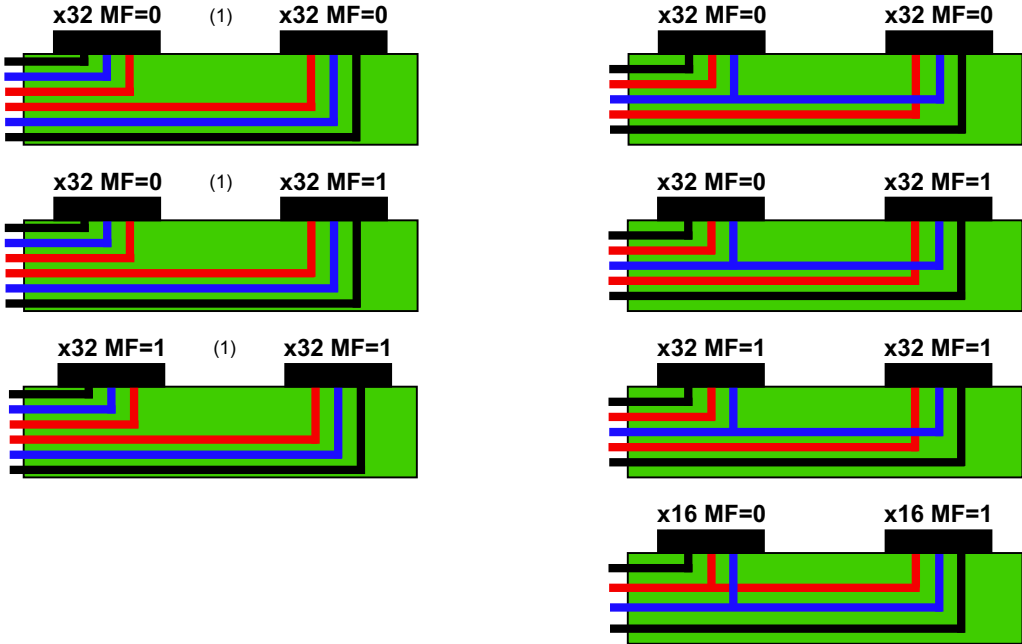
The GDDR5 SGRAM can operate in a x32 mode or a x16 mode to allow a clamshell configuration with a point to point connection on the high speed data signals. The disabled pins in x16 mode will be in Hi-Z state, non-terminating. The x16 mode is detected at power-up on the pin at location C-13 which is EDC1 when configured to MF=0 and EDC2 when configured to MF=1. For x16 mode this pin is tied to VSSQ; the pin is part of the two bytes that are disabled in this mode and therefore not needed for EDC functionality. For x32 mode this pin is active and always terminated to VDDQ in the system or by the controller. The configuration is set with RESET\_n going high. Once the configuration has been set, it cannot be changed during normal operation. Usually the configuration is fixed in the system.

**Table 3: Clamshell Mode and Mirror Function**

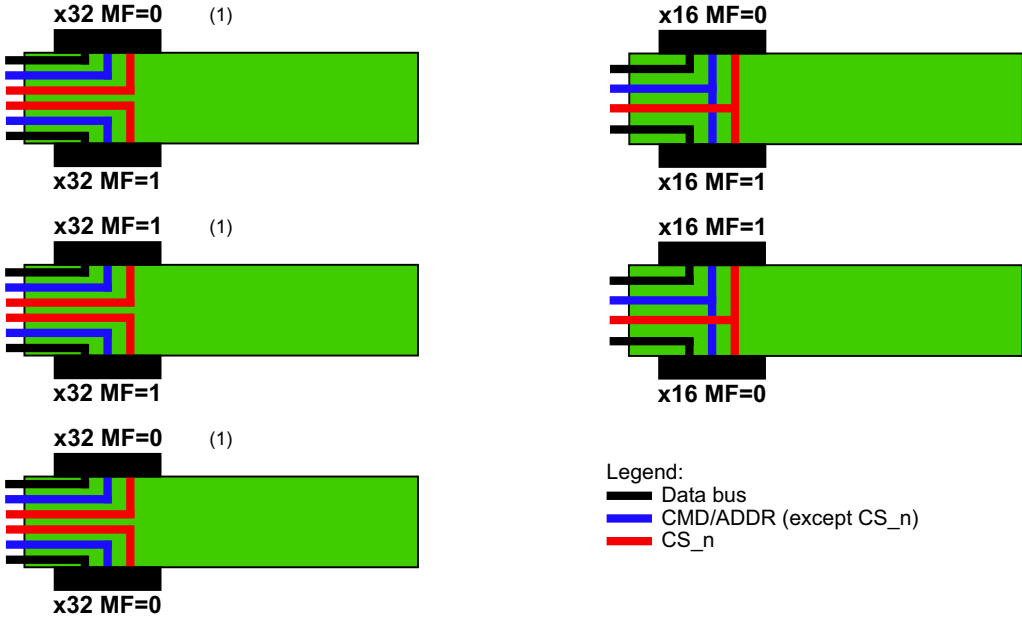
Mode	MF	EDC1 (MF=0) or EDC2 (MF=1)
x16 non-mirrored	VSSQ	VSSQ
x32 non-mirrored	VSSQ	VDDQ (terminated by the system or controller)
x16 mirrored	VDDQ	VSSQ
x32 mirrored	VDDQ	VDDQ (terminated by the system or controller)

Figure 1 shows examples of the board channels and topologies that are supported in GDDR5 in order to illustrate the expected usage of x16 mode and the MF pin.

Single sided configurations



Clamshell configurations



Legend:  
— Data bus  
— CMD/ADDR (except CS\_n)  
— CS\_n

(1) : 32 bit channel is shown as an example; also applies with x16 on a 16 bit channel.

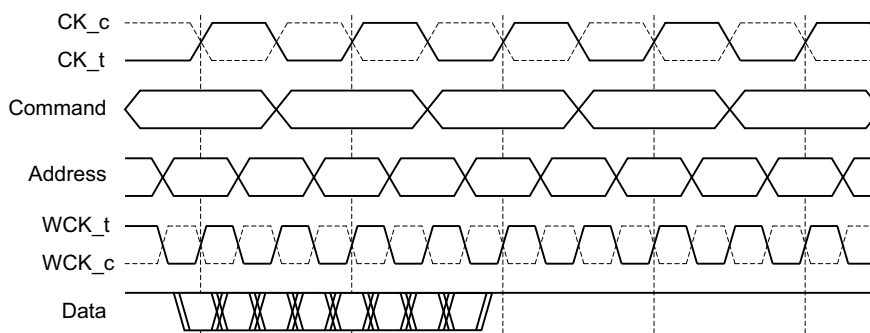
Figure 1: Example GDDR5 PCB Layout Topologies



## 1.4 Clocking

The GDDR5 SGRAM operates from a differential clock CK<sub>t</sub> and CK<sub>c</sub>. Commands are registered at every rising edge of CK<sub>t</sub>. Addresses are registered at every rising edge of CK<sub>t</sub> and every rising edge of CK<sub>c</sub>.

GDDR5 uses a double data rate data interface and an 8n-prefetch architecture. The data interface uses two differential forwarded clocks (WCK<sub>t</sub>, WCK<sub>c</sub>). DDR means that the data is registered at every rising edge of WCK<sub>t</sub> and rising edge of WCK<sub>c</sub>. WCK<sub>t</sub> and WCK<sub>c</sub> are continuously running and operate at twice the frequency of the command/address clock (CK<sub>t</sub>, CK<sub>c</sub>).



Note: the figure shows the relationship between the data rate of the buses and the clocks and is not a timing diagram.

**Figure 2: GDDR5 Clocking and Interface Relationship**

## 1.5 Addressing

The GDDR5 SGRAM uses a double data rate address scheme to reduce pins required on the GDDR5 SGRAM as shown in [Table 4](#). The addresses should be provided to the GDDR5 SGRAM in two parts; the first half is latched on the rising edge of CK<sub>t</sub> along with the command pins such as RAS<sub>n</sub>, CAS<sub>n</sub> and WE<sub>n</sub>; the second half is latched on the rising edge of CK<sub>c</sub>.

The use of DDR addressing allows all address values to be latched in at the same rate as the SDR commands. All addresses related to command access have been positioned for latching on the initial rising edge for faster decoding.

**Table 4: Address Pairs**

Clock Edge	Address Inputs								
Rising CK <sub>t</sub>	BA3	BA2	BA1	BA0	A12	A11	A10	A9	A8
Rising CK <sub>c</sub>	A3	A4	A5	A2	A13	A6	A0	A1	A7

Addressing schemes for x32 mode and x16 mode differ only in the number of valid column addresses, as shown in [Table 5](#).

**Table 5: Addressing Scheme**

	128M x 32	256M x 16
Row address	A0-A13	A0-A13
Column address	A0-A5	A0-A6
Bank address	BA0-BA3	BA0-BA3
Autoprecharge	A8	A8
Page size	2 KB	2 KB
Refresh	16K/32ms	16K/32ms
Refresh period	1.9 μs	1.9 μs

## 1.6 Commands

Table 6: Command Truth Table

Operation	Code	CKE_n (n-1)	CKE_n (n)	CS _n	RAS _n	CAS _n	WE _n	BA3- BA0	A12- A13	A11	A10	A8	A6-A7, A9	A0-A5 (A6)	Notes	
DESELECT	DESEL	L	X	H	X	X	X	X	X	X	X	X	X	X	2,8	
NO OPERATION (NOP)	NOP	L	X	L	H	H	H	X	X	X	X	X	X	X	2,8	
MODE REGISTER SET	MRS	L	L	L	L	L	L	MRA	X	OPCODE					2,3	
ACTIVATE	ACT	L	L	L	L	H	H	BA	RA						2,4	
READ	RD	L	L	L	H	L	H	BA	X	L	L	L	X	CA	2,5,9	
READ with Autoprecharge	RDA	L	L	L	H	L	H	BA	X	L	L	H	X	CA	2,5	
LOAD FIFO	LDFD	L	L	L	H	L	H	BST	X	H	L	L	DATA		2,7	
READ TRAINING	RDTR	L	L	L	H	L	H	X	X	H	H	L	X	X	2	
WRITE without Mask	WR	L	L	L	H	L	L	BA	X	L	L	L	X	CA	2,5	
WRITE without Mask with Autoprecharge	WRA	L	L	L	H	L	L	BA	X	L	L	H	X	CA	2,5	
WRITE with Single Byte Mask	WSM	L	L	L	H	L	L	BA	X	L	H	L	X	CA	2,5	
WRITE with Autoprecharge, Single Byte Mask	WSMA	L	L	L	H	L	L	BA	X	L	H	H	X	CA	2,5	
WRITE with Double Byte Mask	WDM	L	L	L	H	L	L	BA	X	H	L	L	X	CA	2,5	
WRITE with Autoprecharge, Double Byte Mask	WDMA	L	L	L	H	L	L	BA	X	H	L	H	X	CA	2,5	
WRITE TRAINING	WRTR	L	L	L	H	L	L	X	X	H	H	L	X	X	2	
PRECHARGE	PRE	L	L	L	L	H	L	BA	X	X	X	L	X	X	2	
PRECHARGE ALL	PREALL	L	L	L	L	H	L	X	X	X	X	H	X	X	2	
REFRESH	REF	L	L	L	L	L	H	X	X	X	X	X	X	X	6	
POWER-DOWN ENTRY	PDE	L	H	H X X X L H H H			X	X	X	X	X	X	X	X	X	
POWER-DOWN EXIT	PDX	H	L	H X X X L H H H			X	X	X	X	X	X	X	X	X	
SELF-REFRESH ENTRY	SRE	L	H	L	L	L	H	X	X	X	X	X	X	X	6	
SELF-REFRESH EXIT	SRX	H	L	H X X X L H H H			X	X	X	X	X	X	X	X	X	

- Notes: 1. H = logic high level; L = logic low level; X = Don't Care. Signal may be H or L, but not floating.
2. Addresses shown are logical addresses; physical addresses are inverted when address bus inversion (ABI) is activated and ABI\_n=L.
3. BA0-BA3 provide the Mode Register address (MRA), A0-A11 the opcode to be loaded.
4. BA0-BA3 provide the bank address (BA), A0-A13 provide the row address (RA).
5. BA0-BA3 provide the bank address, A0-A5 (A6) provide the column address (CA); no sub-word addressing within a burst of 8.
6. This command is REFRESH when CKE\_n(n) = L, and SELF-REFRESH ENTRY when CKE\_n(n) is H.
7. BA0-BA2 select burst location (BST) and A0-A9, BA3 provide the data.
8. DESELECT and NO OPERATION are functionally interchangeable.
9. In address training mode READ is decoded from the command pins only with RAS\_n = H, CAS\_n = L, WE\_n = H.

## 2. Electrical Characteristics

**Table 7: Absolute Maximum Ratings**

Parameter	Symbol	Min.	Max.	Unit
Voltage on VDD supply relative to VSS	VDD	-0.5	2.0	V
Voltage on VDDQ supply relative to VSSQ	VDDQ	-0.5	2.0	V
Voltage on VREF and inputs relative to VSS	VIN	-0.5	2.0	V
Voltage on I/O pins relative to VSS	VOUT	-0.5	2.0	V
Storage Temperature	TSTG	-55	+150	°C
Short Circuit output current	IOUT	—	50	mA

**Caution:** Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage of the device. This is a stress rating only, and functional operation of the device at these or any other conditions above those indicated in the operational sections of these specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### 2.1 Operating Conditions

**Table 8: Operating Temperature Range**

Parameter	Symbol	Min	Max	Unit
Operating temperature	TC	0	+95	°C

- Notes: 1. Operating temperature TC is the case surface temperature on the center / top side of the DRAM. It specifies the temperature where all DRAM specifications will be supported.  
 2. For measurement conditions, please refer to JEDEC document JESD51-2.

**Table 9: Input Capacitance**

Parameter	Symbol	Min	Max	Unit	Notes
Delta Input/Output Capacitance: DQ, DBI_n, EDC	DCIO	—	0.3	pF	1,2
Delta Input Capacitance: Command and Address	DCI1	—	0.2	pF	1,3,6
Delta Input Capacitance: CK_t, CK_c	DCI2	—	0.1	pF	1,4
Delta Input Capacitance: WCK_t, WCK_c	DCI3	—	0.1	pF	1,5
Input/Output Capacitance: DQ, DBI_n, EDC	CIO	0.9	1.3	pF	1
Input Capacitance: Command and Address	CI1	1.0	1.3	pF	1,6
Input Capacitance: CK_t, CK_c	CI2	1.1	1.3	pF	1
Input Capacitance: WCK_t, WCK_c	CI3	0.9	1.1	pF	1

- Notes: 1. The capacitance is measured according to JEP147 (“PROCEDURE FOR MEASURING INPUT CAPACITANCE USING A VECTOR NETWORK ANALYZER (VNA)”) with VDD, VDDQ, VSS, VSSQ applied and all other pins floating (except the pin under test). VDD=VDDQ=1.5V and on-die termination off.  
 2. DCIO = CIO.MAX - CIO.MIN  
 3. DCI1 = CI1.MAX - CI1.MIN  
 4. DCI2 = Absolute value of C CK\_t - C CK\_c  
 5. DCI3 = Absolute value of C WCK\_t - C WCK\_c  
 6. DCI1 and CI1 apply to RAS\_n, CAS\_n, WE\_n, CS\_n, CKE\_n, ABI\_n, BA3/A3, BA2/A4, BA1/A5, BA0/A2, A12/A13, A11/A6, A10/A0, A9/A1, A8/A7

GDDR5 SGRAMs are designed for 1.5V typical voltage supplies. This GDDR5 SGRAM does also support 1.35V typical voltage supplies. The interface of GDDR5 with 1.5V VDDQ will follow the POD15 specification (JESD8-20A). The interface of GDDR5 with 1.35V VDDQ will follow the POD135 specification Class B (JESD8-21). I/O levels are given here for reference only. All AC and DC values are measured at the ball.

**Table 10: DC Operating Conditions**

Parameter	Symbol	POD15			POD135			Unit	Notes
		min.	typ.	max.	min.	typ.	max.		
Device supply voltage (-70)	VDD	1.552	1.6	1.648	1.3095	1.35	1.3905	V	1
Device supply voltage (-60)	VDD	1.455	1.5	1.545	1.3095	1.35	1.3905	V	1
I/O Supply voltage (-70)	VDDQ	1.552	1.6	1.648	1.3095	1.35	1.3905	V	1
I/O Supply voltage (-60)	VDDQ	1.455	1.5	1.545	1.3095	1.35	1.3905	V	1
Reference voltage for DQ and DBI_n pins	VREFD	0.69 * VDDQ	—	0.71 * VDDQ	0.69 * VDDQ	—	0.71 * VDDQ	V	2,3
Reference voltage for DQ and DBI_n pins	VREFD2	0.49 * VDDQ	—	0.51 * VDDQ	0.49 * VDDQ	—	0.51 * VDDQ	V	2,3,4
External reference voltage for address and command	VREFC	0.69 * VDDQ	—	0.71 * VDDQ	0.69 * VDDQ	—	0.71 * VDDQ	V	5
DC input logic high voltage for address and command inputs	VIHA(DC)	VREFC + 0.15	—	—	VREFC + 0.135	—	—	V	
DC input logic low voltage for address and command inputs	VILA(DC)	—	—	VREFC - 0.15	—	—	VREFC - 0.135	V	
DC input logic high voltage for DQ, DBI_n inputs with VREFD	VIHD(DC)	VREFD + 0.10	—	—	VREFD + 0.09	—	—	V	
DC input logic low voltage for DQ, DBI_n inputs with VREFD	VILD(DC)	—	—	VREFD - 0.10	—	—	VREFD - 0.09	V	
DC input logic high voltage for DQ, DBI_n inputs with VREFD2	VIHD2(DC)	VREFD2 + 0.30	—	—	VREFD2 + 0.27	—	—	V	
DC input logic low voltage for DQ, DBI_n inputs with VREFD2	VILD2(DC)	—	—	VREFD2 - 0.30	—	—	VREFD2 - 0.27	V	
Input logic high voltage for RESET_n, SEN, MF	VIHR	VDDQ - 0.5	—	—	VDDQ - 0.5	—	—	V	
Input logic low voltage for RESET_n, SEN, MF	VILR	—	—	0.3	—	—	0.3	V	
Input logic high voltage for EDC1/2 (x16 mode detect)	VIHX	VDDQ - 0.3	—	—	VDDQ - 0.3	—	—	V	8
Input logic low voltage for EDC1/2 (x16 mode detect)	VILX	—	—	0.3	—	—	0.3	V	8
Input leakage current (any input $0V \leq V_{IN} \leq V_{DDQ}$ ; all other pins not under test = 0V)	IL	-5	—	+5	-5	—	+5	$\mu A$	9
Output leakage current (DQs are disabled; $0V \leq V_{OUT} \leq V_{DDQ}$ )	IOZ	-5	—	+5	-5	—	+5	$\mu A$	10
Output logic low voltage	VOL(DC)	—	—	0.62	—	—	0.56	V	
External resistor value	ZQ	115	120	125	115	120	125	$\Omega$	

- Notes: 1. GDDR5 SGRAMs are designed to tolerate PCB designs with separate VDDQ and VDD power regulators.  
 2. AC noise in the system is estimated at 50 mV peak-to-peak for the purpose of DRAM design.  
 3. Source of reference voltage and control of Reference voltage for DQ and DBI\_n pins is determined by VREFD, Half VREFD and VREFD Offset Mode Registers.  
 4. VREFD Offsets are not supported with VREFD2.  
 5. External VREFC is to be provided by the controller as there is no alternative supply.  
 6. DB, DBI\_n input slew rate must be greater than or equal to 3V/ns for POD15 and 2.7V/ns for POD135. The slew rate is measured between VREFD crossing and VIHD(AC) or VILD(AC) or VREFD2 crossing and VIHD2(AC) or VILD2(AC).  
 7. ADD/CMD input slew rate must be greater than or equal to 3V/ns for POD15 and 2.7V/ns for POD135. The slew rate is measured between VREFC crossing and VIHA(AC) or VILA(AC).

8. VIH<sub>X</sub> and VIL<sub>X</sub> define the input voltage levels for the receiver that detects x32 mode or x16 mode with RESET<sub>n</sub> going high.
9. IL is measured with ODT off. Any input  $0V \leq V_{IN} \leq V_{DDQ}$ ; all other pins not under test = 0V.
10. IOZ is measured with DQs disabled;  $0V \leq V_{OUT} \leq V_{DDQ}$ .

**Table 11: AC Operating Conditions**

Parameter	Symbol	POD15			POD135			Unit	Notes
		min.	typ.	max.	min.	typ.	max.		
AC input logic high voltage for address and command inputs	VIHA(AC)	VREFC + 0.20	—	—	VREFC + 0.18	—	—	V	
AC input logic low voltage for address and command inputs	VILA(AC)	—	—	VREFC - 0.20	—	—	VREFC - 0.18	V	
AC input logic high voltage for DQ, DBI <sub>n</sub> inputs with VREFD	VIHD(AC)	VREFD + 0.15	—	—	VREFD + 0.135	—	—	V	
AC input logic low voltage for DQ, DBI <sub>n</sub> inputs with VREFD	VILD(AC)	—	—	VREFD - 0.15	—	—	VREFD - 0.135	V	
AC input logic high voltage for DQ, DBI <sub>n</sub> inputs with VREFD2	VIHD2(AC)	VREFD2 + 0.40	—	—	VREFD2 + 0.36	—	—	V	
AC input logic low voltage for DQ, DBI <sub>n</sub> inputs with VREFD2	VILD2(AC)	—	—	VREFD2 - 0.40	—	—	VREFD2 - 0.36	V	

Note: For optimum performance it is recommended that signal swings are larger than shown in the table.

**Table 12: Clock Input Operating Conditions**

Parameter	Symbol	POD15		POD135		Unit	Notes
		min.	max.	min.	max.		
Clock input mid-point voltage: CK <sub>t</sub> , CK <sub>c</sub>	VMP(DC)	VREFC - 0.1	VREFC + 0.1	VREFC - 0.1	VREFC + 0.1	V	1,6
Clock input differential voltage: CK <sub>t</sub> , CK <sub>c</sub>	VIDCK(DC)	0.22	—	0.198	—	V	4,6
Clock input differential voltage: CK <sub>t</sub> , CK <sub>c</sub>	VIDCK(AC)	0.40	—	0.36	—	V	2,4,6
Clock input differential voltage: WCK <sub>t</sub> , WCK <sub>c</sub>	VIDWCK(DC)	0.20	—	0.18	—	V	5,7
Clock input differential voltage: WCK <sub>t</sub> , WCK <sub>c</sub>	VIDWCK(AC)	0.30	—	0.27	—	V	2,5,7
Clock input voltage level for CK <sub>t</sub> , CK <sub>c</sub> , WCK <sub>t</sub> , WCK <sub>c</sub> single ended inputs	VIN	-0.3	VDDQ + 0.3	-0.3	VDDQ + 0.3	V	
CK <sub>t</sub> , CK <sub>c</sub> single ended slew rate	CKslew	3	—	2.7	—	V/ns	9
WCK <sub>t</sub> , WCK <sub>c</sub> single ended slew rate	WCKslew	3	—	2.7	—	V/ns	10
Clock input crossing point voltage: CK <sub>t</sub> , CK <sub>c</sub>	VIXCK(AC)	VREFC - 0.12	VREFC + 0.12	VREFC - 0.108	VREFC + 0.108	V	2,3,6
Clock input crossing point voltage: WCK <sub>t</sub> , WCK <sub>c</sub>	VIXWCK(AC)	VREFD - 0.10	VREFD + 0.10	VREFD - 0.09	VREFD + 0.09	V	2,3,7,8

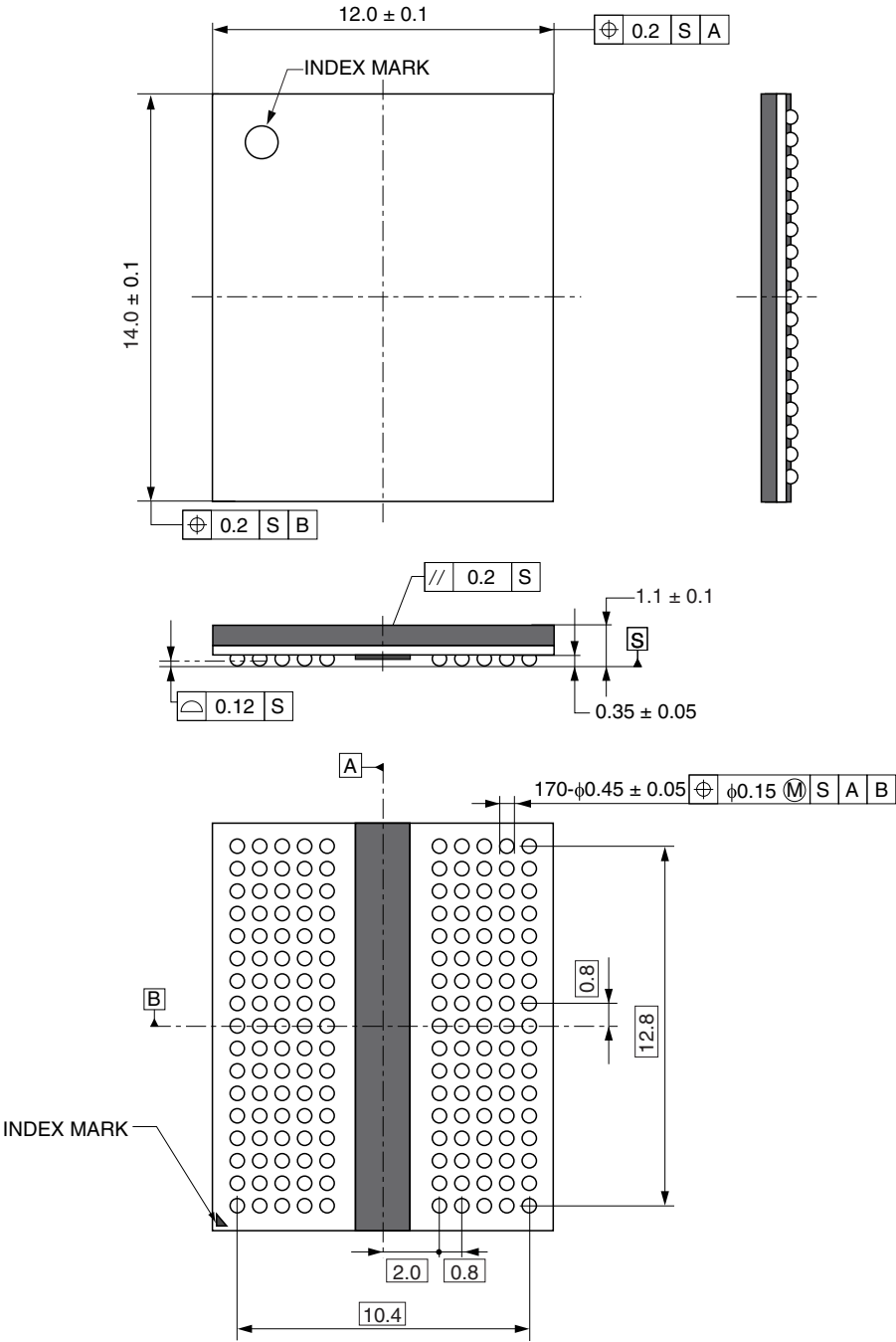
- Notes:
1. This provides a minimum of 0.9V to a maximum of 1.2V, and is nominally 70% of VDDQ with POD15. If POD135, this provides a minimum of 0.845V to a maximum of 1.045V, and is nominally 70% of VDDQ. DRAM timings relative to CK cannot be guaranteed if these limits are exceeded.
  2. For AC operations, all DC clock requirements must be satisfied as well.
  3. The value of VIXCK and VIXWCK is expected to equal 70% VDDQ for the transmitting device and must track variations in the DC level of the same.
  4. VIDCK is the magnitude of the difference between the input level in CK<sub>t</sub> and the input level on CK<sub>c</sub>. The input reference level for signals other than CK<sub>t</sub> and CK<sub>c</sub> is VREFC.
  5. VIDWCK is the magnitude of the difference between the input level in WCK<sub>t</sub> and the input level on WCK<sub>c</sub>. The input reference level for signals other than WCK<sub>t</sub> and WCK<sub>c</sub> is either VREFD, VREFD2 or the internal VREFD.
  6. The CK<sub>t</sub> and CK<sub>c</sub> input reference level (for timing referenced to CK<sub>t</sub> and CK<sub>c</sub>) is the point at which CK<sub>t</sub> and CK<sub>c</sub> cross. Please refer to the applicable timings in the AC timings table.
  7. The WCK<sub>t</sub> and WCK<sub>c</sub> input reference level (for timing referenced to WCK<sub>t</sub> and WCK<sub>c</sub>) is the point at which WCK<sub>t</sub> and WCK<sub>c</sub> cross. Please refer to the applicable timings in the AC Timings table.
  8. VREFD is either VREFD, VREFD2 or the internal VREFD.
  9. The slew rate is measured between VREFC crossing and VIXCK(AC).
  10. The slew rate is measured between VREFD crossing and VIXWCK(AC).

### 3. Package Drawing

#### 170-ball FBGA

Solder ball: Lead free (Sn-Ag-Cu)

Unit: mm



ECA-TS2-0327-02

**NOTES FOR CMOS DEVICES****① PRECAUTION AGAINST ESD FOR MOS DEVICES**

Exposing the MOS devices to a strong electric field can cause destruction of the gate oxide and ultimately degrade the MOS devices operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it, when once it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. MOS devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. MOS devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor MOS devices on it.

**② HANDLING OF UNUSED INPUT PINS FOR CMOS DEVICES**

No connection for CMOS devices input pins can be a cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to  $V_{DD}$  or GND with a resistor, if it is considered to have a possibility of being an output pin. The unused pins must be handled in accordance with the related specifications.

**③ STATUS BEFORE INITIALIZATION OF MOS DEVICES**

Power-on does not necessarily define initial status of MOS devices. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the MOS devices with reset function have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. MOS devices are not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for MOS devices having reset function.

CME0107

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- 2) Usage in exposure to direct sunlight or the outdoors, or in dusty places.
- 3) Usage involving exposure to significant amounts of corrosive gas, including sea air,  $Cl_2$ ,  $H_2S$ ,  $NH_3$ ,  $SO_2$ , and  $NO_x$ .
- 4) Usage in environments with static electricity, or strong electromagnetic waves or radiation.
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M01E1007



**Revision History**

<b>Ver.</b>	<b>Date</b>	<b>Description</b>
1.0	Jul. 2013	Initial version
2.0	Nov. 2013	Status changed from "Preliminary Data Sheet" to "Data Sheet"