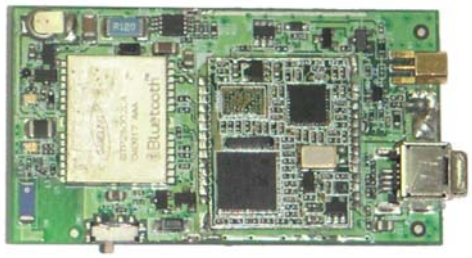

FEATURES

- 12 parallel channel GPS receiver
- 4000 simultaneous time-frequency search bins
- SBAS (WAAS, EGNOS) support
- High Sensitivity:
  - -140dBm acquisition sensitivity
  - -150dBm tracking sensitivity
- Fast Acquisition:
  - < 10 second hot start
  - < 50 second cold start
- 5m CEP accuracy
- Bluetooth version 1.1 compliant
- Compatible with Bluetooth devices with Serial Port Profile (SPP)
- Charger circuitry and connector interface for BLC-2 Li-ION battery
- More than 12 hours of operation

GPS-41BTM

Fast Acquisition Enhanced Sensitivity 12 Channel GPS Sensor Module

The GPS-41BTM is a single board of Bluetooth-GPS module solution for customers who require easy system integration and minimal development risk.

The GPS-41BTM is optimized for good performance and low cost. Its 12 parallel channels and 4000 search bins provide short start-up time and fast signal acquisition. Having fast time-to-first-fix and enhanced sensitivity, the GPS-41BTM offers good navigation performance even in urban canyons.

Satellite-based augmentation systems, such as WAAS and EGNOS, are supported to yield improved accuracy.

The onboard patch antenna provides good signal reception. In situations where the GPS-41BTM is integrated into an application where the patch antenna has limited view of the sky, external active antenna may be directly connected via the MMCX connector to provide improved signal reception.

Class 2 Bluetooth offers up to 10 meters of wireless operation with Bluetooth-enabled devices such as PDA, Tablet-PC or Smart mobile phones.

Ordering Information

Part Number	Description
GPS-41BTM	Bluetooth-GPS Module

Tel 01273 898000 Fax 01273 480661

TECHNICAL SPECIFICATIONS

Receiver Type	12 parallel channel, L1 C/A code
Accuracy	Position 5m CEP Velocity 0.1m/sec
Startup Time	< 10sec hot start < 35sec warm start < 50sec cold start
Signal Reacquisition	< 1s
Sensitivity	-140dBm acquisition -150dBm tracking
Update Rate	1Hz
Dynamics	4G (39.2m/sec^2)
Operational Limits	Altitude < 18,000m or velocity < 515m/sec (COCOM limit, either may be exceeded but not both)
Protocol	NMEA-0183 V3.01 GPGGA, GPGLL, GPGSA, GPGSV, GPRMC, GPVTG, GPZDA 4800 baud, 8, N, 1
Datum	Default WGS-84 User definable
RF Connector	MMCX
Bluetooth Interface	SPP compatible, version 1.1 compliant, class-2 operation, 4dBm output level Up to 10m of operation
LED Indicator	Blue - Bluetooth status Red - Battery low Green - Charging battery
Switch	Push button ON / OFF
Battery Connector	For BLC-2 type Li-ION rechargeable battery (Nokia 3310 NMH-5NX battery)
Input Voltage	5.0V
DC Input Connector	1.3mm MINI JACK (center pin positive, outer contact negative)
Operating Temperature	-40^{o}C ~ +85^{o}C
Humidity	5% ~ 95%

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Li-ION BATTERY CHARGER OPERATION

While the UT-41BTM is connected to the Li-ION rechargeable battery only, without the external 5V DC power source, the red battery-low LED indicator will turn ON when output voltage of the Li-ION falls below 3.45V.

When the 5V DC source is connected to charge the Li-ION battery, the green charging-battery LED indicator will turn ON. The battery will be charging at 48mA during the pre-charge phase until 2.93V is reached. Next, charge current changes to 480mA during the full-charge phase until 4.1V is reached. Afterwards, charge current will decrease gradually until 48mA is reached, and the charge current will fall to a very low value and remain in the trickle charge phase. The green charging-battery LED indicator remains ON until the 5V DC source is disconnected.

MEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

GGA - GPS FIX DATA
Time, position and position-fix related data (number of satellites in use, HDOP, etc.).

Format:
$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>,*<13><CR><LF>

Example:
$GPGGA,104549.04,2447.2038,N,12100.4990,E,1,06,01.7,00078.8,M,0016.3,M,,*5C<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	2447.2038	Latitude in ddmm.mmmm format Leading zeros transmitted
3	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	12100.4990	Longitude in dddmm.mmmm format Leading zeros transmitted
5	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	1	Position fix quality indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode
7	06	Number of satellites in use, 00 ~ 12
8	01.7	Horizontal dilution of precision, 00.0 ~ 99.9
9	00078.8	Antenna height above/below mean sea level, -9999.9 ~ 17999.9
10	0016.3	Geoidal height, -999.9 ~ 9999.9
11		Age of DGPS data since last valid RTCM transmission in xxx format (seconds) NULL when DGPS not used
12		Differential reference station ID, 0000 ~ 1023 NULL when DGPS not used
13	5C	Checksum

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '$' and '*'.

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GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS
Latitude and longitude of current position, time, and status.

Format:
$GPGLL,<1>,<2>,<3>,<4>,<5>,<6>,<7>*<8><CR><LF>

Example:
$GPGLL,2447.2073,N,12100.5022,E,104548.04,A,A*65<CR><LF>

Field	Example	Description
1	2447.2073	Latitude in ddmm.mmmm format Leading zeros transmitted
2	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
3	12100.5022	Longitude in dddmm.mmmm format Leading zeros transmitted
4	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
5	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
6	A	Status, ‘A’ = valid position, ‘V’ = navigation receiver warning
7	A	Mode indicator ‘N’ = Data invalid ‘A’ = Autonomous ‘D’ = Differential ‘E’ = Estimated
8	65	Checksum

GSA - GPS DOP AND ACTIVE SATELLITES
GPS receiver operating mode, satellites used for navigation, and DOP values.

Format:
$GPGSA,<1>,<2>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:
$GPGSA,A,3,26,21,,,09,17,,,,,,,10.8,02.1,10.6*07<CR><LF>

Field	Example	Description
1	A	Mode, ‘M’ = Manual, ‘A’ = Automatic
2	3	Fix type, 1 = not available, 2 = 2D fix, 3 = 3D fix
3	26,21,,,09,17,,,,,,	PRN number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	10.8	Position dilution of precision, 00.0 to 99.9
5	02.1	Horizontal dilution of precision, 00.0 to 99.9
6	10.6	Vertical dilution of precision, 00.0 to 99.9
7	07	Checksum

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GSV - GPS SATELLITE IN VIEW
Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Only up to four satellite details are transmitted per message. Additional satellite in view information is sent in subsequent GSV messages.

Format:
$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,…,<4>,<5>,<6>,<7> *<8><CR><LF>

Example:
$GPGSV,2,1,08,26,50,016,40,09,50,173,39,21,43,316,38,17,41,144,42*7C<CR><LF>
$GPGSV,2,2,08,29,38,029,37,10,27,082,32,18,22,309,24,24,09,145,*7B<CR><LF>

Field	Example	Description
1	2	Total number of GSV messages to be transmitted
2	1	Number of current GSV message
3	08	Total number of satellites in view, 00 ~ 12
4	26	Satellite PRN number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	50	Satellite elevation number, 00 ~ 90 degrees
6	016	Satellite azimuth angle, 000 ~ 359 degrees
7	40	C/No, 00 ~ 99 dB Null when not tracking
8	7C	Checksum

RMC - RECOMMANDED MINIMUM SPECIFIC GPS/TRANSIT DATA
Time, date, position, course and speed data.

Format:
$GPRMC,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,<10>,<11>,<12>*<13><CR><LF>

Example:
$GPRMC,104549.04,A,2447.2038,N,12100.4990,E,016.0,221.0,250304,003.3,W,A*22<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	A	Status, ‘V’ = navigation receiver warning, ‘A’ = valid position
3	2447.2038	Latitude in dddmm.mmmm format Leading zeros transmitted
4	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
5	12100.4990	Longitude in dddmm.mmmm format Leading zeros transmitted
6	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
7	016.0	Speed over ground, 000.0 ~ 999.9 knots
8	221.0	Course over ground, 000.0 ~ 359.9 degrees
9	250304	UTC date of position fix, ddmmyy format
10	003.3	Magnetic variation, 000.0 ~ 180.0 degrees
11	W	Magnetic variation direction, ‘E’ = East, ‘W’ = West
12	A	Mode indicator ‘N’ = Data invalid ‘A’ = Autonomous ‘D’ = Differential ‘E’ = Estimated
13	22	Checksum

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VTG - COURSE OVER GROUND AND GROUND SPEED
Velocity is given as course over ground (COG) and speed over ground (SOG).

Format:
GPVTG,<1>,T,<2>,M,<3>,N,<4>,K,<5>*<6><CR><LF>

Example:
$GPVTG,221.0,T,224.3,M,016.0,N,0029.6,K,A*1F<CR><LF>

Field	Example	Description
1	221.0	True course over ground, 000.0 ~ 359.9 degrees
2	224.3	Magnetic course over ground, 000.0 ~ 359.9 degrees
3	016.0	Speed over ground, 000.0 ~ 999.9 knots
4	0029.6	Speed over ground, 0000.0 ~ 1800.0 kilometers per hour
5	A	Mode indicator 'N' = Data invalid 'A' = Autonomous 'D' = Differential 'E' = Estimated
6	1F	Checksum

ZDA TIME AND DATE

Format:
$GPZDA,<1>,<2>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:
$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>

Field	Example	Description
1	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	25	UTC time: day (01 ... 31)
3	03	UTC time: month (01 ... 12)
4	2004	UTC time: year (4 digit year)
5		Local zone hour Not being output by the receiver (NULL)
6		Local zone minutes Not being output by the receiver (NULL)
7	6C	Checksum

Binary Messages

Please refer to DS-41COM, *Binary Message Protocol Guide* for detailed descriptions on configuration of the NMEA string.

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