Master-Slave Flip-Flop

Master slave construction renders the MC1670 relatively insensitive to the shape of the clock waveform, since only the voltage levels at the clock inputs control the transfer of information from data input (D) to output.

When both clock inputs (C1 and C2) are in the low state, the data input affects only the "Master" portion of the flip-flop. The data present in the "Master" is transferred to the "Slave" when clock inputs (C1 "OR" C2) are taken from a low to a high level. In other words, the output state of the flip-flop changes on the positive transition of the clock pulse.
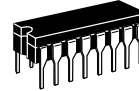
While either C1 "OR" C2 is in the high state, the "Master" (and data input) is disabled.

Asynchronous Set (S) and Reset (R) override Clock (C) and Data (D) inputs.

Power Dissipation = 220 mW typ (No Load)
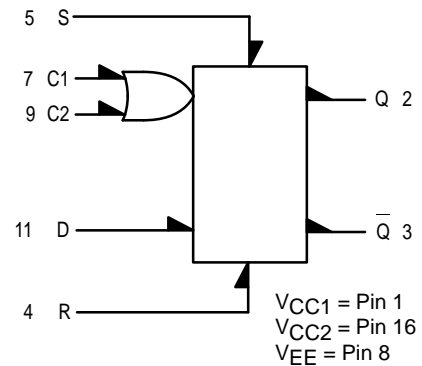f_{Tog} = 350 MHz typ

MC1670

L SUFFIX
CERAMIC PACKAGE
CASE 620–10

TRUTH TABLE

R	S	D	C	Q_{n+1}
L	H	X	X	H
H	L	X	X	L
H	H	X	X	N.D.
L	L	L	L	Q_n
L	L	L	⌐	L
L	L	L	⌐	Q_n
L	L	H	L	Q_n
L	L	H	⌐	H
L	L	H	H	Q_n

ND = Not Defined
C = C1 + C2

LOGIC DIAGRAM

5   S
7   C1
9   C2
Q   2
11 D
$\overline{Q}$ 3
4   R
V_{CC1} = Pin 1
V_{CC2} = Pin 16
V_{EE} = Pin 8

ELECTRICAL CHARACTERISTICS

Characteristic	Symbol	−30°C Min	−30°C Max	+25°C Min	+25°C Max	+85°C Min	+85°C Max	Unit
Power Supply Drain Current	I_E	—	—	—	48	—	—	mAdc
Input Current Set, Reset Clock Data	I_{inH}	 — — —	 — — —	 — — —	 550 250 270	 — — —	 — — —	μAdc
Switching Times Propagation Delay	 t_{pd}	 1.0	 2.7	 1.1	 2.5	 1.1	 2.9	ns
Rise Time (10% to 90%)	t^+	0.9	2.7	1.0	2.5	1.0	2.9	ns
Fall Time (10% to 90%)	t^-	0.5	2.1	0.6	1.9	0.6	2.3	ns
Setup Time	$t_{S"1"}$ $t_{S"0"}$	— —	— —	0.4 0.5	— —	— —	— —	ns
Hold Time	$t_{H"1"}$ $t_{H"0"}$	— —	— —	0.3 0.5	— —	— —	— —	ns
Toggle Frequency	f_{Tog}	270	—	300	—	270	—	MHz

PIN ASSIGNMENT

V_{CC1}	1	16	V_{CC2}
Q	2	15	NC
$\overline{Q}$	3	14	NC
RESET	4	13	NC
SET	5	12	NC
NC	6	11	DATA
CLOCK 1	7	10	NC
V_{EE}	8	9	CLOCK 2

REV 5

MOTOROLA
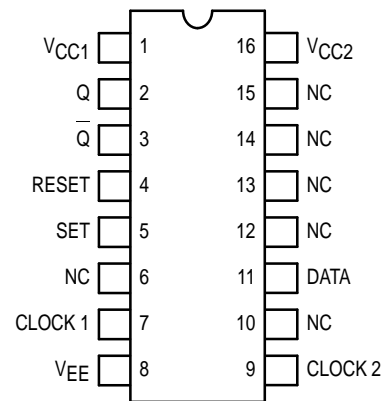
FIGURE 1 — TOGGLE FREQUENCY WAVEFORMS

$T_A = 25°C$

CLOCK INPUT
300
MHZ-MAX

—— +1.11 V

- - - +0.71 V_{BIAS}

—— +0.31 V

Q OR $\overline{Q}$
OUTPUT

600 MV MIN

The maximum toggle frequency of the MC1670 has been exceeded when either:
1. The output peak-to-peak voltage swing falls below 600 millivolts,
   OR
2. The device ceases to toggle (divide by two).
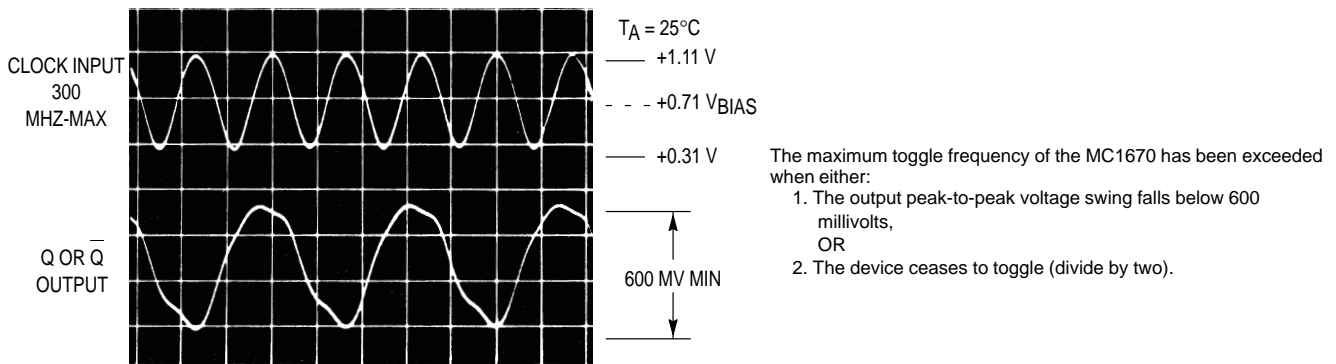
FIGURE 2 — MAXIMUM TOGGLE FREQUENCY (TYPICAL)

V_{Bias}

+1.05
+1.0
+0.95
+0.9
+0.85
+0.8
+0.75
+0.7
+0.65
+0.5
+0.45
+0.4
+0.35
+0.3
+0.25

175   225   275   325   375   425

$T_A = 25°C$
$V_{CC} = +2.0$ VDC
$V_{EE} = -3.2$ VDC

F_{TOG}
(MHZ)
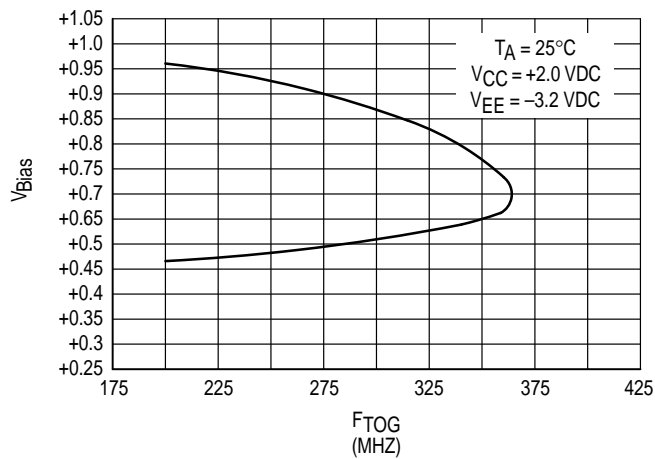
Figure 2 illustrates the variation in toggle frequency with the dc offset voltage (V_{Bias}) of the input clock signal.
Figures 4 and 5 illustrate minimum clock pulse width recommended for reliable operation of the MC1670.

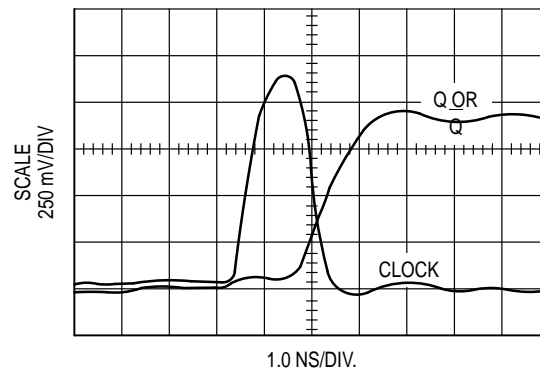### FIGURE 3 — TYPICAL MAXIMUM TOGGLE FREQUENCY
versus TEMPERATURE

$f_{Tog\ max}$, MAXIMUM TOGGLE FREQUENCY (MHz)

400

350

300

250

−30   0   25   50   85

T_A, AMBIENT TEMPERATURE (°C)
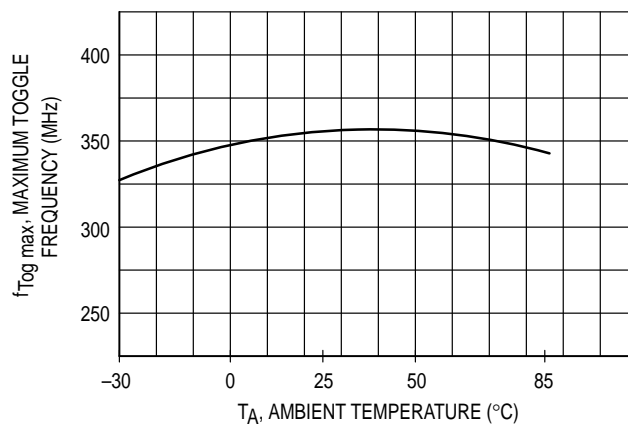
Temperature	−30°C	+25°C	+85°C
V_{Bias}	+0.66 Vdc	+0.71 Vdc	+0.765 Vdc

Note: All power supply and logic levels are shown shifted 2.0 volts positive.

MC1670

FIGURE 4 — MINIMUM "DOWN TIME" TO CLOCK
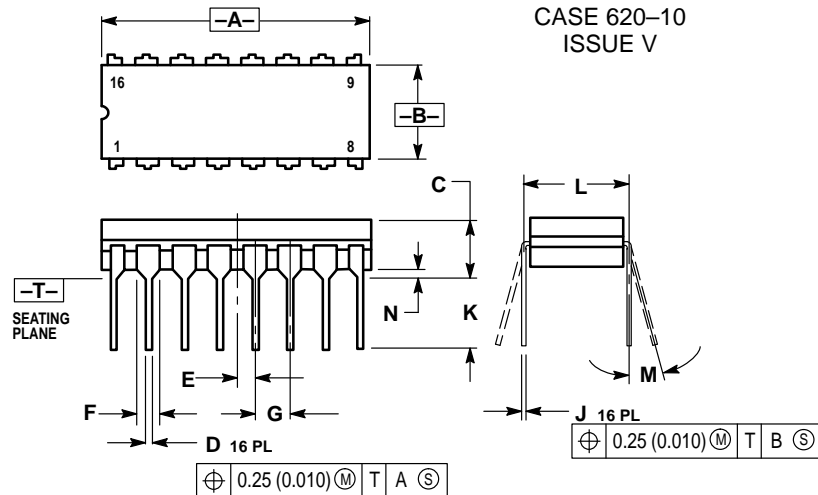**OUTPUT LOAD = 50 Ω**

SCALE
250 mV/DIV

CLOCK

Q OR
Q

1.0 NS/DIV.
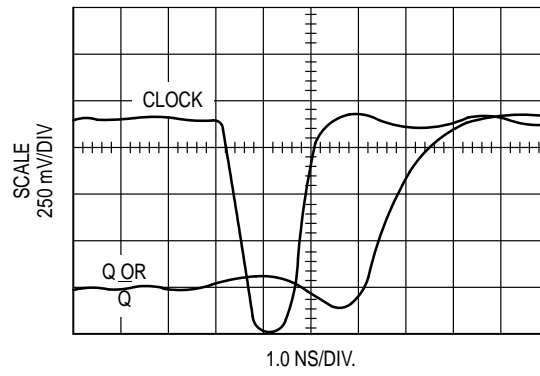
FIGURE 5 — MINIMUM "UP TIME" TO CLOCK
OUTPUT LOAD = 50 Ω

SCALE
250 mV/DIV

Q OR
Q

CLOCK

1.0 NS/DIV.

OUTLINE DIMENSIONS

L SUFFIX
CERAMIC DIP PACKAGE
CASE 620–10
ISSUE V

NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
4. DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.750	0.785	19.05	19.93
B	0.240	0.295	6.10	7.49
C	—	0.200	—	5.08
D	0.015	0.020	0.39	0.50
E	0.050 BSC		1.27 BSC	
F	0.055	0.065	1.40	1.65
G	0.100 BSC		2.54 BSC	
H	0.008	0.015	0.21	0.38
K	0.125	0.170	3.18	4.31
L	0.300 BSC		7.62 BSC	
M	0 °	15 °	0 °	15 °
N	0.020	0.040	0.51	1.01

⊕ 0.25 (0.010) Ⓜ T A Ⓢ

⊕ 0.25 (0.010) Ⓜ T B Ⓢ

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